

# Encoders

## Magnetic Encoders

**Features:**  
 10, 12, 15 or 16 Lines per revolution  
 2 Channels  
 Digital output

### HEAM 1524

Signal output (quadrature)		15 mm technology	channels
Supply voltage	V <sub>CC</sub>	3.0 to 15.0	V DC
Current consumption, typical (V <sub>CC</sub> = 5 V DC)	I <sub>CC</sub>	5 <sup>1)</sup>	mA
Pulse width	P	180 ± 45	°e
Phase shift, channel A to B	Φ	90 ± 45	°e
Logic state width	S	90 ± 45	°e
Cycle	C	360 ± 30	°e
Signal rise/fall time, typical	tr/tf	5 / 0.2	µs
Frequency range	f	up to 7.2	khz
Inertia of code disc	J	2.832 · 10 <sup>-6</sup>	oz-in-sec <sup>2</sup>
Operating temperature range		-40 to +85 (-40 to +185) <sup>2)</sup>	°C (°F)

<sup>1)</sup> current consumption for 1 ppr encoder = 11mA (typical at V<sub>CC</sub> = 5 V DC)

<sup>2)</sup> operating temperature range for 1 ppr encoder is -30 to 85°C (-22 to 185°F)

Encoder type	number of channels	Lines per revolution per channel	in combination with Arsape two phase Stepper motors
HEAM 1524	2	1, 10, 12, 15, 16	AM1524

#### Phase Relationship (with clockwise motor shaft rotation as seen from the shaft end)

HEM1016 thru HEM12.. with 10 or 12 CPR	Channel A leads channel B
HEM1319 thru HEM35.. with 15 CPR	Channel A leads channel B
HEM1319 thru HEM35.. with 1, 10, 12 or 16 CPR	Channel B leads channel A

These incremental shaft encoders in combination with the PRECistep® two phase stepper motors are designed for step verification as well as positioning. There are 12 pulses/revolution per channel is recommended since the motor has 12 poles.

Solid state Hall sensors and a low inertia magnetic disc provide two channels with 90° phase shift.

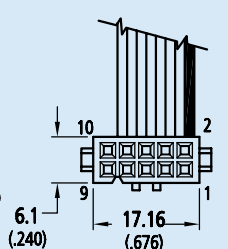
The supply voltage for the encoder, stepper motor as well as the two channel output signals are interfaced with a ribbon cable to a 6-pin connector on motors ≤ 22mm in diameter. Motors ≥ 23mm in diameter the motor voltage is supplied separately.

Details for the Stepper motors and suitable reduction gearboxes are on separate catalog pages.

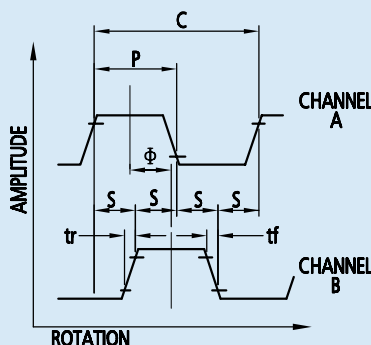
Please note: Velocity (rpm) = f (Hz) x 60/N

#### PIN FUNCTION

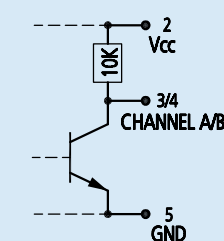
- 1 MOTOR (A+)
- 2 MOTOR (A-)
- 3 V<sub>CC</sub>
- 4 CHANNEL A
- 5 CHANNEL B
- 6 GND
- 7 MOTOR (B+)
- 8 MOTOR (B-)
- 9 N.C.
- 10 N.C.



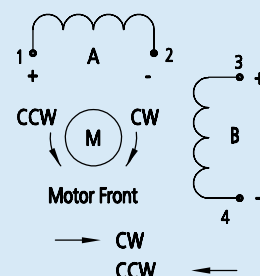
**CONNECTOR (-10P)**  
 (Berg / FCI 71601-110)  
 Polarized  
 .050" Ribbon cable - PVC  
 8 conductors - 28 AWG  
 Mating Connector:  
 Header / FCI 75869-101



**OUTPUT SIGNALS**  
 with clockwise rotation as seen from the shaft end



**OUTPUT CIRCUIT**



	1	2	3	4
Phase A	+	-	-	+
Phase B	+	+	-	-

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